

Paramter setting for PolyLock and PolyCombo.

Click - Device Options, use tab - Add Configuration Settings

The screenshot shows a web-based configuration interface for a device named "Demo EURO cylinder". The interface includes a title bar with a lock icon, the device name, and window controls (trash, help, close). Below the title bar is a "Room: Unassigned" dropdown menu. A "Notifications" section is present, followed by a tabbed interface with tabs for "Control", "Pin codes", "Settings", "Advanced", "Device Options", and "Logs". The "Device Options" tab is active, showing "ZWave options for device #20" with a "learn more" link. A "Manual Z-Wave route (advanced)" field is set to "undefined" with an "explain this" link. An "Update Neighbor Nodes" button is available. Below this is a "Configuration settings" section with a table of variables. The table has columns for "Variable", "Data Size", "Desired Value", and "Current Value". Three rows are shown: Variable 1 (1 byte dec, Desired 5, Current 5), Variable 2 (1 byte dec, Desired 5, Current 5), and Variable 4 (1 byte dec, Desired 2, Current 2). Each row has a small "X" button. An "Add configuration settings" button is at the bottom of the table. Below the table is an "Associations" section with a note: "You must leave *automatically configure* on before this works" and a "learn more" link. A "Group ID:" field and an "Add group" button are also present.

Demo EURO cylinder Room: Unassigned

Notifications

Control Pin codes Settings Advanced Device Options Logs

ZWave options for device #20 [learn more](#)

Manual Z-Wave route (advanced) ([explain this](#)) undefined

Update Neighbor Nodes

Configuration settings

Variable	Data Size	Desired Value	Current Value
1	1 byte dec	5	5
2	1 byte dec	5	5
4	1 byte dec	2	2

Add configuration settings

Associations

You must leave *automatically configure* on before this works [learn more](#)

Group ID: Add group

Parameter #	Function	Size DEC/HEX	Value
0	Reverse Motor direction	1 Byte	0 = normal direction 1 = Reverse direction
1	Motor/relay run time LOCK in sec	1 Byte	1 - 15 sec.
2	Motor/relay run time UNLOCK in sec	1 Byte	1 - 15 sec.
3	Motor Speed	1 Byte	Value 0 - 15 / 0 = fastest 15 = slowest
4	Step Motor drive mode	1 Byte	0 = (Step motor) Wave drive mode. (Less torque, min. power usage, full rotation speed.) 1 = (Step motor) Full drive mode. (Medium torque, max. power usage, full rotation speed.) 2 = (Step motor) Half-step drive mode. (Max. torque, max. power usage, half rotation speed.) 3 = (Relay) Puts DC on connector pin 1 & 2 for the duration of parameter #2 or #3. The polarity of pin 1 & 2 are reversed with respect to open / close command. A close command would set p1+ and p2-, open is p1- and p2+. 4 = (Relay) Lock open sets p1+, p2-, p3z, p4z for parameter #3 seconds. Lock close sets p1z, p2z, p3+, p4-.